## Documentation for LMDZ, Planets version

# Running with only one column: rcm1d in Venus and Titan physics

Sébastien Lebonnois

Latest version: April 3, 2013

#### 1 The rcm1d tool

The file rcm1d.F is located in the phy<planet> directory. For the moment, the tool described here is available for Venus and Titan, though a similar tool exists for Mars and the Generic model.

The goal of this tool is to initialize the model the same way gcm. F does on 3D, but only on a single column, so that the physics may be tested without any dynamics.

It can be compiled (sequential only) with a command like (e.g. for 50 layers):

makelmdz -p venus -d 50 rcm1d

It requires the files rcm1d.def, physiq.def and a file describing the vertical layers (z2sig.def). The 3D run.def is also needed though only to access physiq.def (the other parameters specific to run.def are not read.

**Beware:** The file traceur.def may or may not be present. For the moment, tracers are initialized to 0. If you plan to use them, there will be need for modifications (in rcmld.F).

Using these files and an initial temperature vertical profile defined in the profile.F routine (with options available through rcmld.def), the model is initialized and a first startphy.nc file is written, to be read again at the first call of physiq.

## 2 Specific rcm1d.def file

This file is read by rcmld during initialization. It is very simple and reads values at the beginning of each lines (different from gcm.def). It can be found in the deftank directory. Each line has a comment explaining what the parameter is. The number of timestep per day (third line) is the number of calls to the physics per day, since no dynamics is involved here.

It also includes parameters for the profile. F definition.

## 3 Outputs

It writes the same hist\*.nc as the regular GCM. It also writes a profile.new file containing the vertical profiles of altitude, temperature and stability at the end of the run, and the usual restartphy.nc though it will not be used for a restart, since rcmld starts with the same initial state everytime it is launched.